

# DARPAICE 2002 Symposium

Fally Casy





# Navigation & Guidance

Lt Col Gregory Vansuch, USAF DARPA/SPO 703-248-1547







## Navigation & Guidance

#### **GPX**

High power GPS signals

#### **MEMS INS**

Low cost inertial sensors





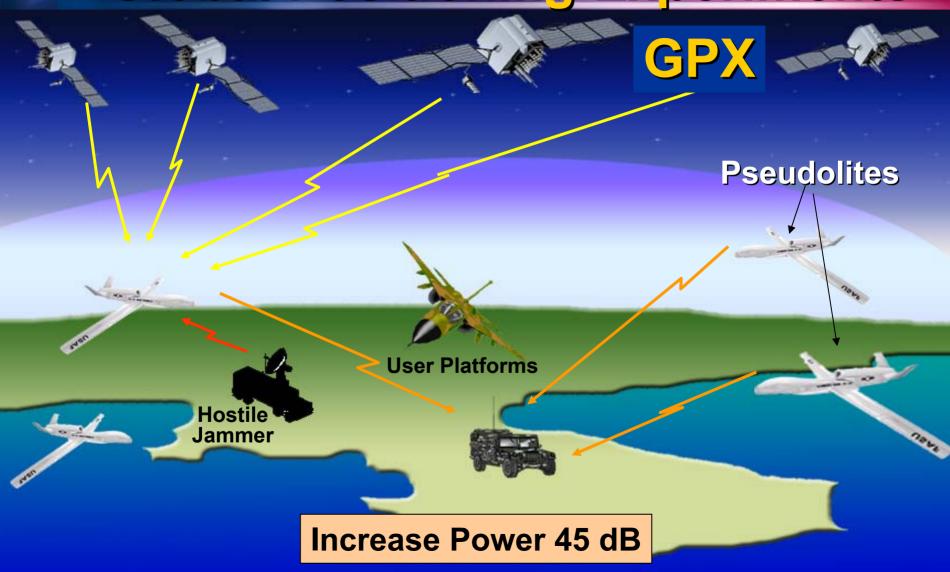
#### **New Initiatives**

- Man-portable navigation
- Urban/indoor navigation
- Inertial navigation <1 deg/hr</p>





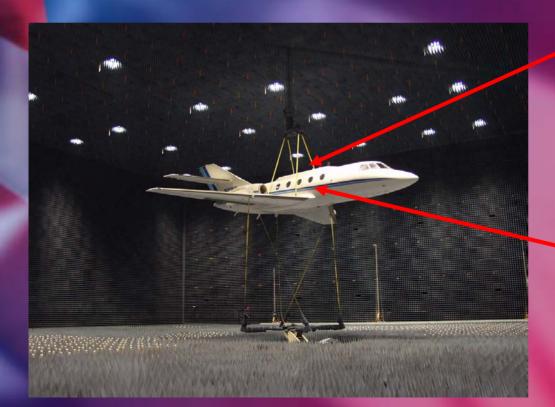
# Global Positioning Experiments





## Digital Beamformer

- Full scale jamming tests in chamber
- Pseudolite protected by 40-55 dB



#### 7 Element Antenna

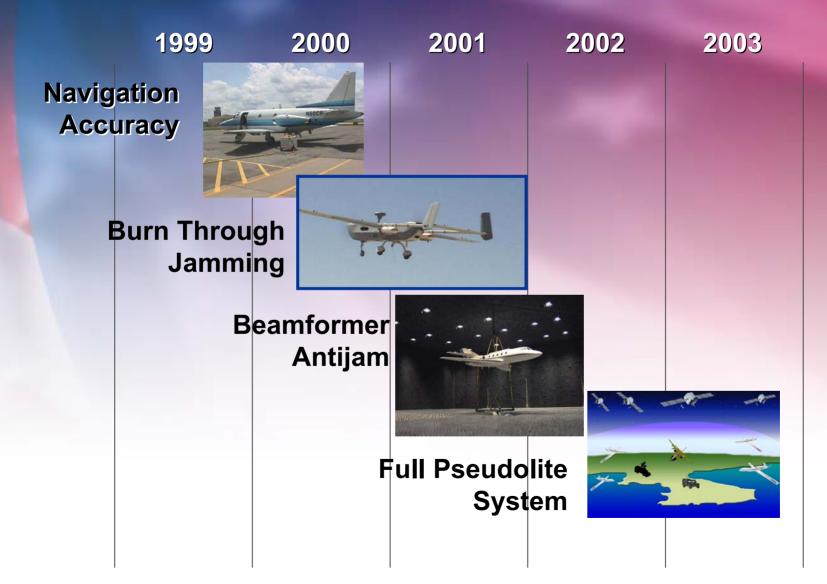


#### **Digital Beamformer**



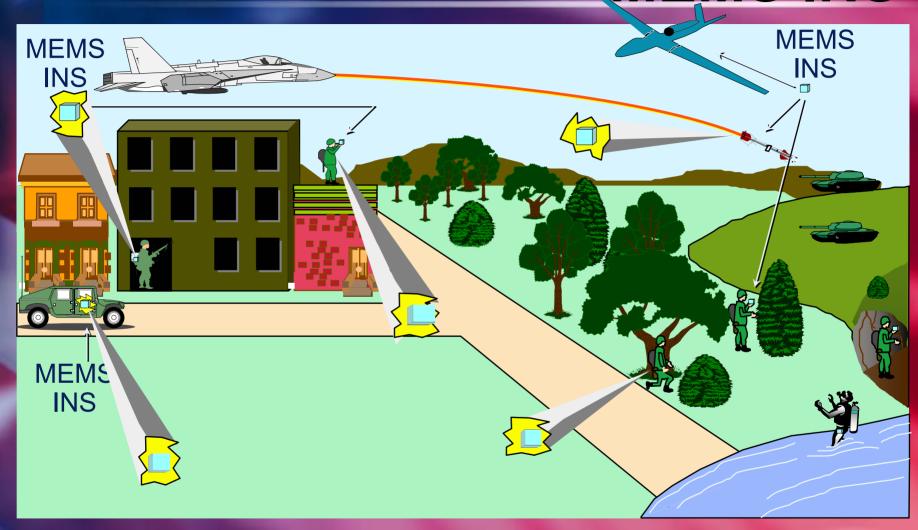


## GPX Testing





## MEMS INS









#### MEMS INS





- 1.0° to 10°/hr Gyro Drift Rate
- <500 mg Accelerometer Bias</li>
- Temperature Range: -54 to 85°C
- Low Power <3 Watts</li>
- Small Size: <10 cu inch</li>







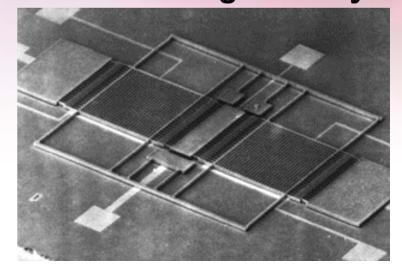
## MEMS Gyroscope



KEARFOTTMicromachined Vibrating
Beam Multisensor



#### **DRAPER - Tuning Fork Gyro**





# MEMS-based Inertial Measurement Units

#### **Draper Laboratory**





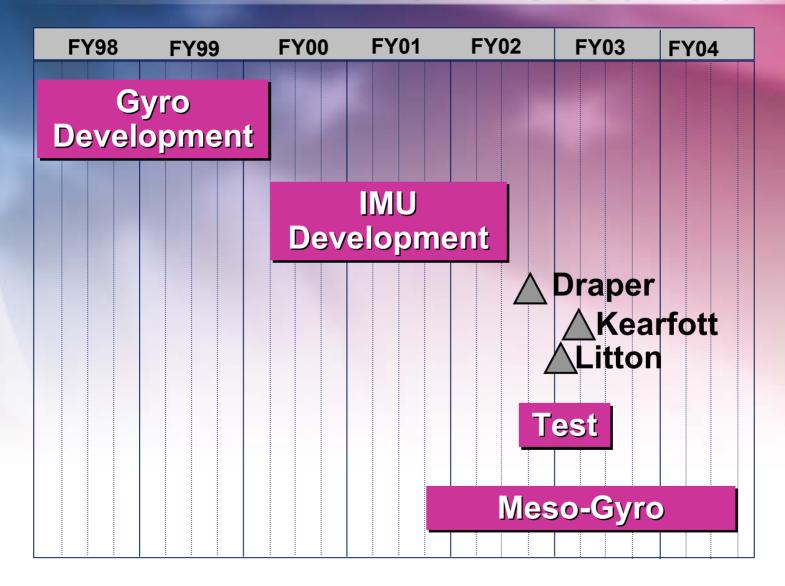
# Kearfott Guidance & Navigation







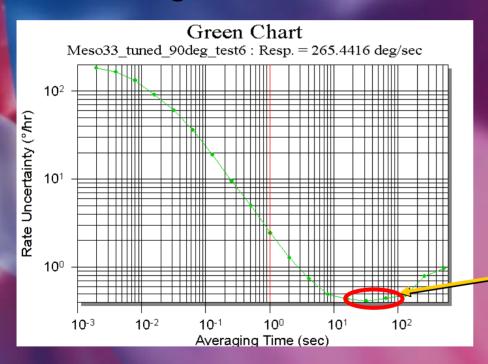
## MEMS-INS Schedule

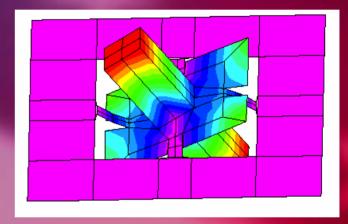




## Meso-Gyroscope

Meso-scale gyroscope offers more accuracy at slight increase of size and cost





074 qealur







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